

Modernization of Conventional Multi Operation Machine with Special Attachment

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Abstract: This paper talks about the traditional machine into CNC machine by actualizing a delicate figuring technique. In the present situation machine assumes an indispensable job in assembling industry and it is efficient, the precision and effectiveness are not up to the dimension. Then again, CNC machine give the ideal precise measurement and productivity, yet its enormous in capital expense. To beat this circumstance, a semi-mechanized methodology towards the ordinary machine is created by utilizing DC engines. That can be constrained by Arduino UNO-microcontroller. The information parameters of the activities the Arduino coding is been produced and exchanged to the UNO board. In the mechanical section, a plan is made to feed the dc motor to the lead screw. On the other hand, in the electronic section, an electronic circuit containing the motor driver circuit is structured so as to control and record the axis movement.

Keywords: lathe, CNC machine, Arduino Microcontroller

1. Introduction

The work is aimed at development of converting conventional lathe machine into smart machine with help of controller or Arduino and motor, motor drives [1]. Lathe machines have been called the mother of machines since they can almost machine any type of component or materials [3]. they have become the ancestral machine which mankind have been used for many advancements and in industries but now they have been overcome with numerical controlled machine which are again revolutionized into CNC which provide high degree of accuracy and precision but their cost are too much for many small scale industries [6] and more over the operators must learn the G-codes and M-codes which are used to control any typical CNC machines[2]. Thus our project is convert a lathe machine in to smart while where the operator can record the memory codes which are calculated by the controller itself and can be repeated multiple number of times with of repeat and record buttons [15]. In this project we have controlled the lathe machine with Arduino controller and motor drivers and record repeat button which helps to save the memory codes of the movements of lead screw and the carriage movement by the bolt and nut mechanism. The motors are connected to the lead screw and the carriage with help of motor drivers which controls the rotation of the motors and provide accurate position for the complete achievement of the accuracy and precision of carriage and the lead screw movement [16].

The arduino board controls the entire operation just by feedback mechanism from the motor drivers and controls their rotation and also controls the record and repeat options [14], which makes the lathe machine into smart machine thus allowing the machine to run continuously for many repeated cycles which makes the machine best suited for batch production in small scale industries.

2. Experimental setup and details

A. Experiment setup

In this venture an endeavor has been made to prepare the regular machine with Digital Intelligence framework (DIS). In order to get more accurate dimensions and easier programming for the operator. There will record button pressing which will record all the action done on the lathe. Upon pressing repeat button, the recorded actions will be repeated just like a CNC machine.



Fig. 1. Experimental setup

B. Experimental details

- DC motor
- Motor module
- Keypad
- Arduino UNO
- Lead screw
- EEPROM

C. Arduino UNO

A microcontroller is a little, ordinarily single chip. PC with the capacity to lead outflags and react to them. The standard way a microcontroller interfaces with the outside world is through info/yield pins. Microcontrollers should likewise have some interface for programming them as memory to store the projects and to give transitory memory space to program execution.

The Arduino UNO has 14 input/yield sticks on one side (marked 0 through 13) and 6 input/yield sticks on the other (named A0 through A5). It is these pins that permit outside data stream all through the microcontroller. The six pins marked A0 through A5 have the simple to computerized transformation (ADC) capacity. This implies you can gauge a simple voltage (somewhere in the range of 0 and 5V) on these pinsto a specific level of exactness. On account of the Arduino, the exactness is 5/1023 or around 5 mV.

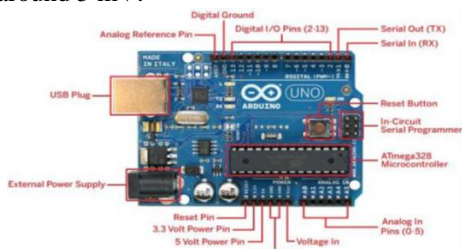


Fig. 2. Arduino UNO

Table 1
Electrical specifications of Arduino

microcontroller	AT mega328P
Operating voltage	5V
Input voltage (recommended)	7-12 V
Input voltage(limit)	6-20V
Digital I/O Pins	14(of which 6 Provide PWN output)
Analog Input Pins	6
PWM Digital I/O Pins	6
DC Current for 3.3V Pin	50mA
Weight of Arduino	25g
Width	53.4mm
Length of Aurdino	68.6mm
Clock speed	16MHz
Electrically Erasable Programmable Read Only Memory (EEPROM)	1KB (AT mega 328P)
SRAM	2KB
Flash Memory	32KB

A. Working

When the operator presses the record button while operating the lathe machine the Arduino controller receives the codes for the precise location of the movement of the tool post and the carriage and saves it in the memory and when the codes are stored. They can be repeated by the push of the repeat button. when the operator presses the repeat button, the Arduino controller access the memory codes for the precise location of the carriage and tool post movement by controlling motor rotation with help of motor module which continuously sends feedback to the controller and thus the carriage and tool post movements are controlled in sequence for the perfect matching

of the protect. The operator can repeat the same procedure for many number of identical product to be machined with the same identical dimension. Thus helping in batch production

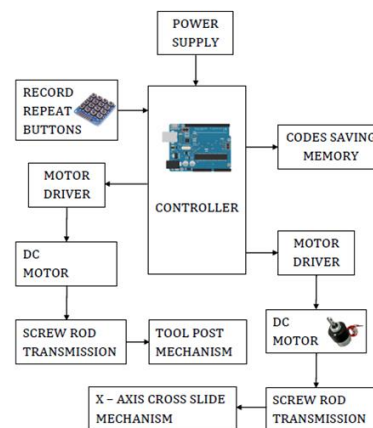


Fig. 3. Basic connection diagram

3. Conclusion

The task "Modernization of Conventional Multi Operation Machine with Special Attachment' which utilizes the Arduino is working with attractive condition to meet the resistances and furthermore the nature of the project. Thus this is useful to improve the exactness and accuracy of the parts to be machined in ordinary machine. This is only a model of the undertaking which can be tried adversary continuous ecological issues and other application.

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